

$v = \frac{ds}{dt} = \dot{s}$	$a = \frac{dv}{dt} = \dot{v} = \frac{d^2s}{ds^2} = \ddot{s}$	$v \, dv = a \, ds$	$\vec{v} = \frac{d\vec{r}}{dt}$	$\vec{a} = \frac{d\vec{r}}{dt} = \frac{d^2\vec{r}}{dt^2}$
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$v = v_0 + a_c \, t$	$s = s_0 + v_0 \, t + \frac{1}{2} a_c t^2$	$v^2 = v_0^2 + 2a_c \, (s - s_0)$
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$\vec{v} = v \, \vec{e}_t = \rho \, \dot{\beta} \, \vec{e}_t$	$\dot{e}_t = \dot{\beta} e_n$	$\vec{a} = a_n \vec{e}_n + a_t \vec{e}_t$
	$\rho = \frac{\left[1 + \left(\frac{dy}{dx}\right)^2\right]^{\frac{3}{2}}}{\frac{d^2y}{dx^2}}$	$a_n = \frac{v^2}{\rho} = \rho \dot{\beta}^2 = v \dot{\beta}$
		$a_t = \dot{v} = \ddot{s}$

$\vec{r} = r \, \vec{e}_r = \rho \, \dot{\beta} \, \vec{e}_t$	$\vec{v} = \dot{r} \vec{e}_r + r \dot{\theta} \vec{e}_\theta$	$\vec{a} = a_r \vec{e}_r + a_\theta \vec{e}_\theta$
$\dot{\vec{e}}_r = \dot{\theta} \vec{e}_\theta$	$\dot{\vec{e}}_\theta = -\dot{\theta} \vec{e}_r$	$a_r = \ddot{r} - r \dot{\theta}^2$
		$a_\theta = r \ddot{\theta} + 2 \dot{r} \dot{\theta} = \frac{1}{r} \frac{d}{dt} (r^2 \dot{\theta})$

$\vec{v} = v_r \vec{e}_r + v_\theta \vec{e}_\theta + v_\phi \vec{e}_\phi$	$\vec{a} = a_R \vec{e}_R + a_\theta \vec{e}_\theta + a_\phi \vec{e}_\phi$
$v_r = \dot{R}$	$a_r = \ddot{R} - R \dot{\phi}^2 - R \dot{\theta}^2 \cos^2 \phi$
$v_\theta = R \dot{\theta} \cos \phi$	$a_\theta = \frac{\cos \phi}{R} \frac{d}{dt} (R^2 \dot{\theta}) - 2 R \dot{\theta} \dot{\phi} \sin \phi$
$v_\phi = R \dot{\phi}$	$a_\phi = \frac{1}{R} \frac{d}{dt} (R^2 \dot{\phi}) + R \dot{\theta}^2 \sin \phi \cos \phi$

$\sum \vec{F} = m \vec{a}$	$dU = \vec{F} \cdot d\vec{r}$	$P = \vec{F} \cdot \vec{v}$
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$U'_{1-2} = \Delta T + \Delta V_g + \Delta V_e$	$\int_{t_1}^{t_2} \sum \vec{F} \, dt = \vec{G}_2 - \vec{G}_1$	$\int_{t_1}^{t_2} \sum \vec{M}_o \, dt = \vec{H}_{o_2} - \vec{H}_{o_1}$
$T = \frac{1}{2} m v^2$	$\vec{G} = m \vec{V}$	$\sum \vec{M}_o = \vec{r} \times \sum \vec{F} = \vec{r} \times m \vec{v}$
$V_g = mgh$		$\vec{H}_o = \vec{r} \times \vec{G}$
$V_e = \frac{1}{2} k x^2$		

$\vec{v}_A = \vec{v}_B + \vec{v}_{A/B}$	$\vec{a}_A = a_B + \vec{a}_{A/B}$
$\vec{v}_{A/B} = \vec{\omega} \times \vec{r}_{A/B}$	$\vec{a}_{A/B} = (\vec{a}_{A/B})_n + (\vec{a}_{A/B})_t$
	$(\vec{a}_{A/B})_n = \vec{\omega} \times (\vec{\omega} \times \vec{r}_{A/B}) = \frac{v_{A/B}^2}{r} \vec{e}_n = r \omega^2 \vec{e}_n$
	$(\vec{a}_{A/B})_t = \vec{\alpha} \times \vec{r}_{A/B}$
$\vec{v}_A = \vec{v}_P + \vec{v}_{rel}$	$\vec{a}_A = a_P + 2 \omega \times \vec{v}_{rel} + \times \vec{a}_{rel}$

$T = \frac{1}{2} m \vec{v}^2 + \Sigma \left(\frac{1}{2} m_i \dot{\vec{r}}_{m_i/G} ^2 \right)$	$\vec{G} = m \vec{V}$	$\vec{r} = \frac{\Sigma m_i \vec{r}_i}{m}$	$\Sigma \vec{F}_i = m \vec{a}$	$\Sigma \vec{F}_i = \dot{\vec{G}}$
$\vec{H}_G = \Sigma (\vec{r}_{m_i/G} \times m_i \dot{\vec{r}}_{m_i/G})$	$\vec{H}_P = \vec{H}_G + \vec{r}_{G/P} \times m \vec{v}$ $(\vec{H}_P)_{rel} = \Sigma (\vec{r}_{m_i/P} \times m_i \dot{\vec{r}}_{m_i/P})$			

$\Sigma \vec{M}_o = \dot{\vec{H}}_o$	$\Sigma \vec{M}_P = \dot{\vec{H}}_G + \vec{r}_{G/P} \times m \vec{a}_G$	$\Sigma \vec{M}_P = (\dot{\vec{H}}_P)_{rel} + \vec{r}_{G/P} \times m \vec{a}_P$
$\Sigma \vec{M}_G = \dot{\vec{H}}_G$		

$\Sigma \vec{F} = m \vec{a}$	$\Sigma \vec{M}_G = \bar{I} \vec{\alpha}$	
$\Sigma \vec{M}_o = I_o \vec{\alpha}$	$\Sigma \vec{M}_P = I_G \vec{\alpha} + \vec{r}_{G/P} \times m \vec{a}_G$	$\Sigma \vec{M}_P = I_P \vec{\alpha} + \vec{r}_{G/P} \times m \vec{a}_P$

$U = \int M \, d\theta$	$P = M \omega$		
$T = \frac{1}{2} m \vec{v}^2 + \frac{1}{2} \bar{I} \omega^2$	$T = \frac{1}{2} I_o \omega^2$	$T = \frac{1}{2} I_C \omega^2$	

$\vec{G} = m \vec{v}$	$\vec{\vec{H}} = \bar{I} \vec{\omega}$		
$Slender \, rod \, \bar{I} = \frac{1}{12} m l^2$	$Disk \, \bar{I} = \frac{1}{2} m r^2$	$I = \bar{I} + m d^2$	